



### **ENabling SafE Multi-Brand Platooning for Europe**

Introduction, Marika Hoedemaeker

# **ENSEMBLE:** Facts & Figures



The ENSEMBLE project is coordinated by TNO in collaboration with: • The European truck manufacturers: DAF, DAIMLER Truck, IVECO, MAN, SCANIA, VOLVO Group (Volvo trucks and Renault trucks) CLEPA represents the European suppliers of automotive equipment and components. Suppliers: Bosch, Brembo, Continental, NXP, WABCO, ZF • ERTICO: Link to the European Truck Platooning Community Knowledge partners:

IDIADA, Université Gustave Eiffel, KTH, VU

Brussel.

- Innovation Action no. 769115
- 4 year EU project (June 2018– March 2022)
- 20 million EUR EC funding
- 19 partners representing the full value chain of the automotive sector

# **EUCAR - ENSEMBLE**





Strengthen the Competitiveness of the European Automotive Manufacturers

through
Strategic
Collaborative
Research &
Innovation.



## **Objectives**





# Pave the way for the adoption of multi-brand truck platooning in Europe HOW?

- Aligning and working on standardization of multi-brand specifications
- Implementing Platooning as a support system
- Demonstrating differently branded trucks in one platoon under real world traffic conditions
- Assessing impacts on traffic flow, business models, driver behavior and fuel economy

### **Truck platooning & ENSEMBLE**





#### **Truck platooning**

The linking of two or more trucks in convoy, using connectivity technology and automated driving support systems (ACEA)



### **Societal impact**

Potential to improve road safety, reduce emissions and increase transport efficiency An integral *multi-brand* approach is needed to move further



#### **ENSEMBLE's goal**

Harmonise multi-brand specifications, realising a Multi-brand V2V communication protocol leading to standards for *multi-brand* truck interoperability



#### **Platooning Levels**

ENSEMBLE defines two ways of platooning & will implement and demonstrate one of them

# **Platooning levels**



# **Support VS Autonomous function**



Platooning as Support function	Platooning as Autonomous function
Driver responsible	Driver out of the loop
Longitudinal support	Both longitudinal and lateral control
Coordinated speed, gap and braking	ODD still to be defined
THW ~ 1,5 s	THW ~ 0,5 and 1.5 s
	Driver only in first truck
Quick deployment on road	First intro in confined areas

**ENSEMBLE** final demonstration will show the Support function. **ENSEMBLE** will provide specifications for both functions

# **Benefits**



### **ENSEMBLE** benefits





- Paves the way towards autonomous platooning (comparable to SAE L4) by providing the important corner stones for the required technologies
- communication technology
- brake performance estimation
- architecture for strategic and service layer (platoon matching)
- Defines platooning technology for standardization across
   Europe as a necessary step towards autonomous platooning

# **ENSEMBLE** benefits: Support Function



#### 1. Improvement of traffic safety

- Safer distance control compared to current driving conditions
- Faster reaction to potentially dangerous braking situations because of V2V
- Possibilities of coordinated braking manoeuvres

#### 2. Improvement of traffic flow

- More stable string of following trucks, even more improved when combined with strategic traffic controller
- Standard communication protocol between all trucks on the road to improve awareness for other cooperative vehicles.

### 3. V2X validated specifications

### 4. Improvement in fuel consumption

SAE (drive alone vehicle): 4-10% fuel reduction for the following vehicle (with following distance 1,5s, speed 80 km/h; based on literature). Compared to current real traffic conditions: a reduced effect on fuel consumption due to the following distances already driven.



### **ENSEMBLE** benefits: Autonomous Function







Safety by design, not dependent on platoon driver behaviour in the following vehicles anymore



Standard communication protocol between all trucks on the road, easy to adopt for passenger cars



Improved traffic flow because of constant smaller following distance (i.e 20m)



Improvement in driver productivity and possible solution for current driver shortage problem



Positive effect on fuel consumption due to potential decreased headways

### Where are we?



2019

April:

2018

June:

Kick off

Definition of specifications

May: General Assembly

October:

Communication functions & tactical layer SW ready for implementation

2020

February:

Periodic Review

**Until March:** 

COVID 19 Start Implementation on trucks, first 3-brand tests on test tracks

2021

Further implementations

3-brand testing

Impact studies Spec of autonomous function

23 Sept 2021:

Public demo Spain

2022

March 2022:

Presentation of final (impact) results

Final event Belgium

### **Main achievements**



- Public Demo!
- Many hours of aligning, specifying and implementation
- Many hours of testing: mono-brand, duo-brand, triple-brand, 7-brand
- Many public deliverables can already be found on our website

Multi-brand platooning works in real life

# Very proud!









# Thank you for your attention



Consortium leader Marika.hoedemaeker@tno.nl